

# Supplementary Materials for ECCV 2024 paper SA-DVAE: Improving Zero-Shot Skeleton-Based Action Recognition by Disentangled Variational Autoencoders

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## A Hyperparameter Search Space and Sensitivity

We show our search space and initial values in Tab. A.

**Table A:** Hyperparameter search space and initial values

No.	Hyperparameter	Space	Initial
1	$\beta_x$ and $\beta_y$	(0, 1.0)	
2	Learning rate's exponent	(-6.0, -3.0)	-5
3	Batch size	{32, 64, 128, 256}	64
4	Discriminator steps $n_d$	{1, 2, 3, ..., 16}	10
5	Hidden dim. of $z_x^r$ and $z_y$	{128, 144, 160, ..., 256}	192
6	Hidden dim. of $z_x^v$	{8, 12, 16, ..., 32}	8

We first fix No. 2~6 and randomly sample No. 1 in uniform distribution 5 times. We choose the one generating the highest GZSL harmonic mean on the validation set. Then we fix No. 1 and randomly sample No. 2~6 100 times.

Table B shows the influence of  $\beta_x$  and  $\beta_y$  on the experiments of Tables 6 and 7 in the main paper. As reported in Table 5 in the main paper, we use  $\beta_x$  as 0.023 and  $\beta_y$  as 0.011 because they perform best on the validation set. We leave out  $\beta_x$  and  $\beta_y \geq 0.2$  because their performance is low.

## B Feature Extractors

We show an example by re-organizing Tables 6 and 7 in the main paper as Tab. C. Their dataset, splits, and hyperparameters are the same and the only

**Table B:** Sensitivity of  $\beta_x$  and  $\beta_y$  on ZSL and GZSL metrics.

$\beta_x$	$\beta_y$	ZSL	GZSL		
		<i>Acc</i>	<i>Acc<sub>s</sub></i>	<i>Acc<sub>u</sub></i>	<i>H</i>
0.010	0.010	83.60	81.14	67.14	73.48
0.050	0.010	<b>84.39</b>	73.87	73.24	73.55
0.010	0.050	83.13	77.61	71.22	74.28
0.050	0.050	83.62	70.74	74.23	72.44
0.100	0.100	82.79	75.96	68.86	72.24
0.200	0.200	76.12	71.79	62.90	67.05
0.023	0.011	84.20	78.16	72.60	<b>75.27</b>

difference lies in feature extractors. Experimental results show that extractors matter and our proposed ST-GCN+CLIP works best.

**Table C:** Average ZSL accuracy and GZSL metrics (%) of different feature extractors under the random split setting on NTU-60.

Feature Extractors	ZSL	GZSL		
	<i>Acc</i>	<i>Acc<sub>s</sub></i>	<i>Acc<sub>u</sub></i>	<i>H</i>
ST-GCN [5] + Sentence-BERT [4]	74.38	71.39	61.02	65.80
PoseC3D [1] + CLIP [3]	81.84	83.48	66.89	74.27
ST-GCN [5] + CLIP [3]	<b>84.20</b>	78.16	72.60	<b>75.27</b>

## C Combining with Existing Methods

To potentially improve our performance, we combine our method with pose canonicalization on skeleton data [2] and enhanced class descriptions by a large language model proposed in SMIE [6]. We will discuss the details and experimental results in the following sections.

### C.1 Pose Canonicalization on Skeleton Data

The difference in the forward direction of the skeleton data introduces additional noise into the training process. Therefore, we implement the method proposed by Holden *et al.* [2] to canonicalize the skeleton data by rotating them so that they face the same direction. We compute the cross product between the vertical axis and the average vector of the left and right shoulders and hips to determine the new forward direction of the body. We then apply a rotation matrix to canonicalize the pose.

Tables D and E present the experimental results under random split settings listed in Table 5 of the main paper. In zero-shot settings, we observe that canonicalization of skeleton data has little effect on model performance. For generalized zero-shot settings, we note a slight decrease in both seen and unseen accuracies. We hypothesize that this is because canonicalization reduces the variation in the skeleton dataset. This reduction in diversity limits the range of examples the model encounters during training, which may ultimately impair its ability to generalize effectively.

**Table D:** Average ZSL accuracy (%) under the random split setting on the NTU-60, NTU-120, and PKU-MMD datasets.

Method	NTU-60	NTU-120	PKU-MMD
	55/5 split	110/10 split	46/5 split
SA-DVAE	<b>84.20</b>	<b>50.67</b>	66.54
SA-DVAE + pose canonicalization	84.03	50.04	<b>67.56</b>

**Table E:** Average GZSL metrics: seen class accuracy  $Acc_s$ , unseen class accuracy  $Acc_u$ , and their harmonic mean  $H$  (%) under the random split setting on the NTU-60, NTU-120, and PKU-MMD datasets.

Method	NTU-60			NTU-120			PKU-MMD		
	55/5 splits			110/10 split			46/5 split		
	$Acc_s$	$Acc_u$	$H$	$Acc_s$	$Acc_u$	$H$	$Acc_s$	$Acc_u$	$H$
SA-DVAE	78.16	72.60	<b>75.27</b>	58.09	40.23	<b>47.54</b>	58.49	51.40	<b>54.72</b>
SA-DVAE + pose canonicalization	72.84	69.85	71.31	56.78	35.22	43.47	54.13	50.60	52.30

## C.2 Enhanced Class Descriptions by a Large Language Model (LLM)

Zhou *et al.* [6] propose to use an LLM to augment class descriptions with richer action-related information and we directly compare our and their methods by using their augmented descriptions. We report results using the same setting for random split and list our hyperparameters in Table F, and generate results shown in Tables G and H, which show that SA-DAVE outperforms SMIE using augmented descriptions in both ZSL and GZSL protocols and LLM-augmented descriptions significantly improve unseen accuracy while marginally decreasing seen accuracy. This is consistent with the pattern observed in the ablation study, indicating that the models achieve a more balanced prediction with minimal bias toward seen or unseen classes.

**Table F:** Settings for LLM-augmented class descriptions under the random split setting.

	NTU-60	NTU-120
Skeleton Feature Extractor	ST-GCN [5]	
Text Feature Extractor	CLIP-ViT-B/32 [3]	
Epochs	10	
Optimizer	Adam	
No. of unseen classes	5	10
Optimizer Momentum	$\beta_1 = 0.9, \beta_2 = 0.999$	
Batch size	32	24
Learning rate	4.94e-05	2.13e-05
Weights of $D_{KL}$ in $\mathcal{L}_{VAE}$	$\beta_x = 0.023, \beta_y = 0.011$	
Weight of $\mathcal{L}_T$	$\lambda_2 = 0.011$	
Discriminator steps $n_d$	4	16
Hidden dim. of $z_x^r$ and $z_y$	96	304
Hidden dim. of $z_x^v$	8	12

**Table G:** ZSL accuracy (%) with LLM-augmented class descriptions on the NTU-60 and NTU-120 datasets.

Method	NTU-60	NTU-120
	55/5 split	110/10 split
SMIE [6]	65.08	46.40
SMIE + augmented text [6]	70.89	52.04
SA-DVAE	84.20	50.67
SA-DVAE + augmented text	<b>87.61</b>	<b>57.16</b>

**Table H:** GZSL metrics (%) with LLM-augmented class descriptions on the NTU-60 and NTU-120 datasets.

Method	NTU-60			NTU-120		
	55/5 splits			110/10 split		
	<i>Acc<sub>s</sub></i>	<i>Acc<sub>u</sub></i>	<i>H</i>	<i>Acc<sub>s</sub></i>	<i>Acc<sub>u</sub></i>	<i>H</i>
SA-DVAE	78.16	72.60	75.27	58.09	40.23	47.54
SA-DVAE + augmented text	74.54	76.50	<b>75.51</b>	53.32	48.36	<b>50.72</b>

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